Boyang Zhang

Contact Information	133 Hudson Hall Durham, NC 27708 +1 919-660-5201	boyang.zhang@duke.edu LinkedIn Profile Personal Website	
Research Interests	Dynamics and control; Multi-agent robotics; Robot mot automated vehicles; Unmanned aerial vehicles; Autonomo Collision avoidance; Wheeled robot; Legged robot; Soft ro Smart manufacturing; Renewable energy; Smart power Control theory; Optimization theory; Intelligent civil infras	tion planning; Connected and us surface/underwater vehicles; bot; Human-robot interaction; grids; System identification; tructures; Operations research.	
Education	Ph.D., Civil and Environmental Engineering	Sept. 2023	
	Duke University, Durham, United States		
	 Dissertation: Control through constraint. Committee: 		
	 Committee: Henri Gavin (Chair), Earl Dowell, Jerome Lynch, Michael Zavlanos, Dennis Bernstein. Highlights: 		
	 2022–2023 Duke Graduate/Professional Academic E Preparing Future Faculty Fellow (22 fellows out of all Bass Instructional TA Fellow (four fellows out of all Summer Research Fellow (two fellows out of all third students in seven Physical Sciences and Engineering Certificate in College Teaching Certificate in Teaching Writing 	xemplar of the Year Duke Ph.D. students/postdocs) Duke Ph.D. candidates) d year and beyond Duke Ph.D. departments)	
	M.S., Electrical and Computer Engineering	Sept. 2023	
	Duke University, Durham, United States		
	 Research project: An instantaneous nonlinear optimal co Committee: Vahid Tarokh (Chair), Tyler Bletsch, Ehsan Abadi. 	ontrol paradigm via constraints.	
	M.Eng., Ocean and Naval Architectural Engineerin	g Oct. 2017	
	Memorial University (MUN), St. John's, Canada		
	 Thesis: Improving time-domain prediction of vortex-indu Committee: Wei Qiu (Chair), David Molyneux, James Yang. Highlights: 	aced vibration for marine risers.	
	 GPA: 4.0/4.0 Fellow of the School of Graduate Studies (awarded program's final-year students.) 	l to less than 10% of a degree	
	B.Eng., Ocean and Naval Engineering	July 2013.	
	Tianjin University (TJU), Tianjin, China		
Research Experience	Graduate Research Assistant Duke University, Durham, United States	June 2018 – Sept. 2023	

- Developed centralized and decentralized frameworks for the navigation and control of hundreds of agents based on extensions of Gauss's principle of least constraint (GPLC).
- Resolved the deadlocks naturally among double integrators by a constraint reformulation.
- Originated computationally simple, centralized and decentralized control methods for single/multiple fully nonlinear quadrotors based on generalizations of GPLC.
- Formulated computationally simple, centralized and decentralized control methods for single/multiple nonholonomic wheeled mobile robots based on extensions of GPLC.
- Derived the input-output stability of nonlinear dynamical systems based on conic sectors.
- Led and managed the publication of **seven** first-authored papers in top venues in the field of control and optimization and won **two** best paper awards.
- Presented my doctoral research at **eight** control conferences and won **two** best presentation awards.
- Wrote proposals to win more than **\$197,000** of competitive fellowships and grants to fund my doctoral work.

Graduate Research Assistant

Memorial University, St. John's, Canada

- Derived and compared time-domain models to predict vortex-induced vibration (VIV).
- Re-developed an in-house finite-element program in Fortran for mooring line analysis.
- Designed a model test of two cylinders under VIV interaction at high Reynolds numbers.
- Wrote applications to win more than **\$54,000** of competitive scholarships to fund my Master's work.

Technology Intern

American Bureau of Shipping, Houston, United States

- Researched the rules and regulations from seven classification societies: ABS, DNV-GL, LR, BV, NK, CCS, and KR.
- Upgraded the ABS notation comparison database with 371 modifications.

Undergraduate Research Assistant

Tianjin University, Tianjin, China

- Analyzed extreme loading scenarios for an offshore jack-up platform in ANSYS.
- Assisted in coupling the hull heave-moonpool fluid motion for a SPAR platform.
- Conducted ship resistance/propulsion tests at Tianjin University Towing Tank.

Refereed JOURNAL PUBLICATIONS

- 1. Zhang, B. and Gavin, H.P. Gauss's Principle with Inequality Constraints for Multiagent Navigation and Control. IEEE Transactions on Automatic Control, vol. 67, no. 2, pp. 810-823, 2022, doi: 10.1109/TAC.2021.3059677. (impact factor: 6.8; Google Scholar Metrics ranking in Automation & Control Theory: 3/20)
- 2. Zhang, B. and Gavin, H.P. Decentralized Control of Multiagent Navigation Systems. IEEE/CAA Journal of Automatica Sinica (JAS), vol. 9, no. 5, pp. 922-925, 2022, doi: 10.1109/JAS.2022.105569.

(impact factor: 11.8; Scopus ranking in Control and Optimization: 1/121)

3. Zhang, B. and Qiu, W. Improving Time-Domain Prediction of Vortex-Induced Vibration for Marine Risers. Marine Systems & Ocean Technology, vol. 13, no. 1, pp. 13-25, 2018, doi: 10.1007/s40868-017-0041-3.

Jan. 2015 – May 2015

Mar. 2012 – June 2013

June 2014 – June 2017

PEER- REVIEWED CONFERENCE	 Zhang, B. and Gavin, H.P. Computationally Efficient Trackin Drive Wheeled Mobile Robots. <i>Proceedings of the 2023 Amer</i> (ACC), pp. 891-896, 2023, doi: 10.23919/ACC55779.2023.10 	ng Control of Differential <i>rican Control Conference</i> 0156242.		
PUBLICATIONS	 Zhang, B. and Gavin, H.P. Decentralized Unified Position-Attitude Control of Nonlinear UAVs. Proceedings of the 61st IEEE Conference on Decision and Control (CDC), pp. 5214-5219, 2022, doi: 10.1109/CDC51059.2022.9992624. Zhang, B. and Gavin, H.P. Unified Position-Attitude Control of A Nonlinear Quadrotor Swarm. Proceedings of the 2022 American Control Conference (ACC), pp. 4030-4035, 2022, doi: 10.23919/ACC53348.2022.9867205. 			
	 Zhang, B. and Gavin, H.P. Unified Position and Attitude Con Quadrotor. Proceedings of the 2021 American Control Conf 1069, 2021, doi: 10.23919/ACC50511.2021.9483358. 	trol of a Fully Nonlinear <i>erence (ACC)</i> , pp. 1064-		
Conference Presentations	 2023 American Control Conference, San Diego, CA. 2023 Southeast Control Conference, Gainesville, FL. Best Presentation Award 	May 2023 Feb. 2023		
	• 61st IEEE Conference on Decision and Control. Cancún. Mexi	ico. Dec. 2022		
	• 2022 American Control Conference. Atlanta, GA.	June 2022		
	• IEEE/CAA JAS Symposium Series 1 (virtual).	Feb. 2022		
	• 60th IEEE Conference on Decision and Control. Austin, TX.	Dec. 2021		
	• 2021 Southeast Control Conference Blacksburg VA	Oct. 2021		
	• 2021 American Control Conference, New Orleans, LA.	May 2021		
Teaching Experience	Co-instructor of Uncertainty, Design, and Optimization (Duke University, Durham, United States	CEE 201) Spring 2023		
	Gave four guest lectures and weekly 75-minute recitations to 20Assisted in preparing lecture materials and homework questionHeld weekly office hours.	undergraduate students. ns/solutions.		
	Instructor of Robust Control (ME 592) Duke University, Durham, United States	Spring 2018		
	 Developed lecture notes. Gave lectures to seven people, including five undergraduate/gr professors. 	aduate students and two		
	 Graduate Teaching Assistant Duke University, Durham, United States Gave three tutorial labs to 51 students in EGR 201. Gave two guest lectures to 15 students in CEE 690.06. Held weekly office hours. 	Fall 2021/Spring 2022		
	 Graded the assignments and lab reports. Mechanics of Solids (EGR 201) 	Fall 2021		
	Undergraduate course, 54 students. Risk and Resilience in Engineering (CEE 690.06)	Spring 2022		

Peer-

Graduate/Undergraduate course, 15 students.

	Graduate Teaching Assistant Memorial University. St. John's. Canada	Jan. 2014 – Dec. 2015
	 Gave tutorial lectures and labs to 344 students. Generated the solutions to assignments and exams. 	
	• Graded the assignments and lab reports. Mechanical Vibrations (EN 6933)	Fall 2014/2015
	Undergraduate course, 106/105 students. Fluid Mechanics (EN 4961)	Spring 2015
	Undergraduate course, 91 students.	
	Dynamics and Maneuvering of Ocean Vehicles (EN 70) Undergraduate course, 20 students.	35) Spring 2014
	Marine Propulsion (EN 5020) Undergraduate course, 22 students.	Winter 2014
Grants,	International/National Level:	
Awards, & Honors	• Outstanding Self-financed Students Abroad Award (\$6,000) China Scholarship Council	June 2023
nonons	Best Presentation Award	Feb. 2023
	2023 Southeast Control Conference	
	• 2022 Society for Risk Analysis Annual Meeting Student Award (Society for Risk Analysis	\$75) Nov. 2022
	• 2022 CDC Student Travel Award and Workshop Support (\$825) 61st IEEE Conference on Decision and Control (CDC)	Sept. 2022
	• 2022 ACC Student Travel Grant (\$445)	Apr. 2022
	2022 American Control Conference (ACC)	
	• 2022 ACC Best Student Paper Award Nominee	Nov. 2021
	• Selected oral presenter	Jan. 2023/Oct. 2021
	 Southeast Control Conference 60th IEEE CDC Student Travel Support (\$125) 60th IEEE Conference on Designer and Control (CDC) 	Sept. 2021
	• 60th IEEE CDC Best Student Paper Award Nominee	Sept. 2021
	• 2021 ACC Student Registration Grant (\$100)	Apr. 2021
	2021 American Control Conference (ACC)	1
	• Short-Term Innovative Research Grant (\$60,000) U.S. Army Research Office	Sept. 2019
	• Mitacs Accelerate Award (\$10,000) Mitacs Canada	Jan. 2015
	 Offshore Technology Research Fellowship (\$42,000) Network Grand Control of Contro	Sept. 2013/2014
	Excellent Volunteer	Sept. 2012
	World Economic Forum (Tranjin Summer Davos) • Triple A Student	Man 9000
	• Imple-A Student Department of Education, Hebei Province, China	Mar. 2009
	University Level:	

•	Duke DEFINE Academy Research Talk Competition – 1st place	Oct. 2023
•	Duke DEFINE Academy Fellow (26 out of 82 applicants nationwide)	Sept. 2023
•	Senol Utku Annual Award with High Distinction	May 2023

	 Duke In the Spotlight Award Duke Graduate/Professional Academic Exemplar of the Year Duke Graduate School Conference Travel Award (\$700) Preparing Future Faculty Fellowship (\$500) Duke Graduate School Conference Travel Award (\$525) Summer Research Fellowship (\$12,561) Bass Instructional Teaching Assistant Fellowship (\$29,770) Auburn Preparing Future Faculty Fellow (200 out of 800+) Senol Utku Annual Award with Highest Distinction (\$350) The only student participant/speaker at Duke Libraries fundraising event Fellow of the MUN School of Graduate Studies Duke Graduate School Fellowship (\$85,479) McGill Engineering Doctoral Award (\$96,000) (declined) MUN Outstanding Teaching Assistant Award Nominee MUN School of Graduate Studies Scholarship (\$2,000) Sept. TJU Excellent Student Leadership Scholarship TJU Advanced Student in Volunteer Service 	May 2023 Mar. 2023 Nov. 2022 July 2022 May 2022 Jan. 2022 Dec. 2021 Sept. 2021 Apr. 2019 Nov. 2017 Aug. 2017 Mar. 2017 May 2016 2013/2014 Dec. 2011
CERTIFICATION	 Science Communication Duke University, Durham, United States Offshore Systems for Oil & Gas Production and Renewable Energy University of Maine, Orono, United States Arctic/Subarctic Offshore Engineering American Society of Mechanical Engineers (ASME) Fundamentals of Riser & Flexible Pipe Engineering American Society of Mechanical Engineers (ASME) The Fundamentals of Project Management Memorial University, St. John's, Canada Design and Analysis of Floating Platforms John Halkyard Associates, Houston, United States 	Mar. 2023 Mar. 2016 May 2015 May 2015 May 2015 Oct. 2014
Invited Reviewership	IEEE/CAA Journal of Automatica Sinica IEEE Open Journal of Control Systems IEEE Control Systems Letters IEEE Conference on Decision and Control IEEE Access Information Sciences American Control Conference	
Professional Societies	Member of IEEE Control Systems Society	
Languages & Skills	 Language: Fluent in English; native in Chinese (Simplified and Traditional). Computer: IAT_EX, Matlab, Fortran, C, Linux, SolidWorks, Gnuplot, AutoCAD, ANSYS 	J.
References	Available upon request.	